

# Time-Domain Method of Lines Applied to Planar Guided Wave Structures

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**Abstract** — A new time-domain method for the analysis of wave propagation and scattering in a planar transmission structure is developed in which the concept of the method of lines is used. The analytical process incorporated along one of the three dimensions has been executed for each line independently (one-dimensional process) or for one set of lines (two-dimensional process) depending on whether or not the structure contains metallic strips at the dielectric interface boundary. A simple numerical example is presented as a demonstration of the above two processes of the method, and its validity is shown by comparison with other data.

## I. INTRODUCTION

THE TIME-DOMAIN analysis of microwave planar transmission structures provides an alternative to the frequency-domain approach and is also useful for studying the behavior of pulsed signals in structures such as high-speed digital circuits. A typical time-domain analysis requires discretization of a three-dimensional space into a three-dimensional mesh. Usually, a large computer storage and a long computation time are required. An additional problem of these methods is the difficulty in handling open boundaries.

The method proposed in this paper originates from the fact that most of the discontinuities appearing in the planar transmission structures are located on the substrate surface and the space below and above this surface is uniform and homogeneous. We wish to solve the problem by discretizing only in a two-dimensional surface on the substrate where the discontinuity is located. This is possible if the wave-scattering information in the direction perpendicular to the substrate surface is available analytically. The proposed method actually incorporates this process. The method is somewhat similar to a frequency-domain analysis called the method of lines [1].

The method entails the discretization of the structure by a number of lines perpendicular to the substrate surface as shown in Fig. 1. At the specified time, a spatial diagonalization transform of the field distribution at each intersection of these lines with the substrate surface is calculated by Maxwell's equations discretized only in the  $x$  and  $z$  directions, which are parallel to the substrate surface. The field information in the  $y$  direction is obtained analytically at each point and time. This information can be found

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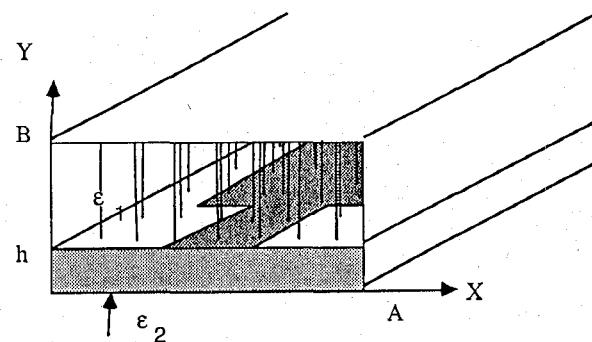


Fig. 1. Typical planar transmission line structure with discontinuity and its discretization example for the analysis.

from the inverse Fourier transform of the solution of the frequency-domain Helmholtz equation in the  $y$  direction.

One may wonder what is happening to the wave-scattering phenomena that are occurring everywhere in the waveguide, not only on each line. This question is natural, because in other time-domain methods the electromagnetic fields at one mesh point interact with those at all six neighboring mesh points in the  $x$ ,  $y$ , and  $z$  directions. In the proposed method, the fields at any point on one discretization line do not appear to interact with those on a similar point on another line. It should be emphasized that this is not the case. As we will see shortly, the spatial diagonalization transformation introduced in this method has the property that the real field as a function of (discretized)  $x$  and  $z$  is transformed to another discretized quantity (transformed field) which contains the real field quantities at all  $x$  and  $z$  values. Therefore, the analytical information in the  $y$  direction in the transformed domain already contains the interaction between lines. Since analytical expressions are used for the field variation in the  $y$  direction, this method can easily handle the case where the top wall is removed, whereby the structure is open in the  $y$  direction.

## II. METHOD

Let us consider a simple two-dimensional structure as a test case. The formulation for such a structure is simple, yet it contains all essential features of the proposed method. As shown in Fig. 2, the problem is a partially filled rectangular waveguide with/without metallization at the dielectric interface excited by an electric field,  $E_z$ , infinite in length and uniform in the  $z$  (axial) direction. The

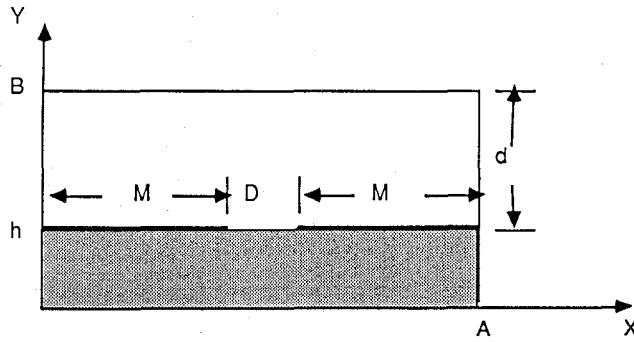


Fig. 2. The cross-sectional structure of a finned rectangular waveguide.

problem is now a two-dimensional one. This problem corresponds to finding the time-domain behavior of the pulsed input in the given structure and the cutoff frequencies of various TM modes in the frequency domain [2].

Because of the excitation, only  $E_z$ ,  $H_x$ , and  $H_y$  exist and  $\partial/\partial z = 0$ . The time-domain equations, discretized in the  $x$  direction only, are given by

$$-\mu \partial [H_x]/\partial t = \partial [E_z]/\partial y \quad (1a)$$

$$-\mu \partial [H_y]/\partial t = [D_x^e][E_z]/\Delta x \quad (1b)$$

$$\epsilon(y) \partial [E_z]/\partial t = -[D_x^e]'[H_y]/\Delta x - \partial [H_x]/\partial y \quad (1c)$$

$$[D_{xx}^e][E_z]/(\Delta x)^2 + \partial^2 [E_z]/\partial^2 y \\ - \mu \epsilon(y) \partial^2 [E_z]/\partial^2 t = 0 \quad (1d)$$

where  $[D_x^e]$ ,  $[D_{xx}^e]$  are difference operators in which the sidewall boundary condition is incorporated [1] and given by

$$[D_x^e] = \begin{bmatrix} -1 & & & \\ & \ddots & & 0 \\ 1 & & \ddots & -1 \\ & \ddots & & 1 \\ 0 & & & \end{bmatrix}$$

and

$$[D_{xx}^e] = \begin{bmatrix} -2 & 1 & & & 0 \\ -1 & -2 & 1 & & \\ & \ddots & \ddots & \ddots & \\ & & 1 & -2 & 1 \\ 0 & & & 1 & -2 \end{bmatrix}. \quad (2)$$

The variables  $[E_z]$ ,  $[H_x]$ , and  $[H_y]$  are the column vectors where the  $i$ th element represents the fields along  $i$ th line and are functions of  $y$  and  $t$ .

Since  $[D_{xx}^e]$  is a real symmetric matrix, there exists a real orthogonal matrix  $[T_x^e]$  that transforms  $[D_{xx}^e]$  into a diagonal matrix  $[d_{xx}^e]$  and is given by [1]

$$[T_x^e]_{ik} = \sqrt{2/(N+1)} \sin [ik\pi/(N+1)] \\ \text{for } i, k = 1 \text{ to } N \quad (3)$$

$$[d_{xx}^e]_{i+1,i} = 2 \sin [i\pi/(2N+2)] \\ \text{for } i = 1 \text{ to } N \quad (4)$$

where  $N$  is the total number of discretized lines for  $E_z$ .

We can now transform  $[E_z]$ , etc., into a transform  $[\tilde{E}_z] = [T_x^e]'[E_z]$ , etc., where the superscript  $t$  stands for transpose. The transform of (1d) is

$$(1/\Delta x)^2 [d_{xx}^e] [\tilde{E}_z] + \partial^2 [\tilde{E}_z]/\partial^2 y \\ - \mu \epsilon(y) \partial^2 [\tilde{E}_z]/\partial^2 t = 0. \quad (5)$$

Depending on the boundary conditions at the interface, the problems can be classified into two groups.

(I) Problem with no metallization at the interface:

$$[E_z(t, y = h^+)] = [E_z(t, y = h^-)] \\ \text{for all } t \text{ and } i \quad (6a)$$

$$[H_x(t, y = h^+)] = [H_x(t, y = h^-)] \\ \text{for all } t \text{ and } i. \quad (6b)$$

(II) Problem with partially metallized interface:

$$[E_z(t, y = h^+)] = [E_z(t, y = h^-)] \\ \text{for all } t \text{ and } i \quad (7a)$$

$$[H_x(t, y = h^-)] - [H_x(t, y = h^+)] = [J_z(t, y = h)] \\ \text{for all } t \text{ and } i \quad (7b)$$

$$[E_z(t, y = h)] = 0 \\ \text{for all } t \text{ and } i \text{ on } M. \quad (7c)$$

Group (I) contains no metallization at the dielectric interface boundary so that the boundary condition is unchanged along the transformed direction. Group (II) contains metallic strips at the dielectric interface boundary so that the nonuniform boundary condition results along the transformed direction.

#### A. Uniform Boundary Problem: One-Dimensional Process

Notice that without any metallization at the dielectric interface boundary, the structure in Fig. 2 becomes a partially filled rectangular waveguide. Since the boundary condition is independent of  $i$ , (5) can be solved for each  $i$ . Using the separation of variable technique, one can obtain a typical Sturm-Liouville differential equation for the  $y$ -dependent solution. The solution for the  $i$ th line is

$$\tilde{E}_{zi}(y, t) = \begin{cases} \sum_n (A_{ni} \cos \omega_{ni} t + B_{ni} \sin \omega_{ni} t) \\ \cdot \sin K_{1ni}(b - y) & \text{(in region I)} \\ \sum_n (A_{ni} \cos \omega_{ni} t + B_{ni} \sin \omega_{ni} t) \\ \cdot (\sin K_{1ni}d / \sin K_{2ni}h) \sin K_{2ni}y & \text{(in region II)} \end{cases} \quad (8)$$

where  $K_{1ni}$ ,  $K_{2ni}$ , and  $\omega_{ni}$  are determined by the characteristic transcendental equation

$$K_{1ni} \cos K_{1ni}d \sin K_{2ni}h + K_{2ni} \sin K_{1ni}d \cos K_{2ni}h = 0 \quad (9)$$

$$[(K_{1ni})^2 - d_{xxi}^3/(\Delta x)^2]/\mu \epsilon_1 \\ = [(K_{2ni})^2 - d_{xxi}^3/(\Delta x)^2]/\mu \epsilon_2 \quad (10)$$

$$\omega_{ni}^2 = [(K_{1ni})^2 - d_{xxi}^3/(\Delta x)^2]/\mu \epsilon_1. \quad (11)$$

From this point on, there are basically two approaches. If the initial conditions for  $E_z$  and its time derivative are given, their diagonalization transforms are readily formed. From those quantities, one can find  $A_{ni}$  and  $B_{ni}$ . Then, the field at any point at any time can be extracted from the inverse transform of (8) via  $[E_z(y, t)] = [T_x^e][\widetilde{E}_z(y, t)]$ .

An alternative method is an application of the time-stepping procedure. From the initial condition for  $E_z$  and its transform  $\widetilde{E}_z$ , one can find  $A_{ni}$  at time  $t = 0$  in (8), which will be called  $A_{ni}^N$  with  $N = 0$ . With the causality condition, the transforms of (1a)–(1c) can be discretized in time as a time-stepping iteration. Expressing the solution (8) in the form

$$\widetilde{E}_{zi}^N(y) = \begin{cases} \Sigma_n A_{ni}^N \sin K_{1ni}(b - y) & \text{(in region I)} \\ \Sigma_n A_{ni}^N (\sin K_{1ni}d / \sin K_{2ni}h) \sin K_{2ni}y & \text{(in region II)} \end{cases} \quad (12)$$

and similar ones for  $\widetilde{H}_{xi}$  and  $\widetilde{H}_{yi}$  at the time  $(N + 1/2)$ , one can implement a leapfrog-type iteration scheme to calculate these coefficients. The real field at  $y = y_0$  at the  $N$ th time step can be obtained by invoking the inverse transformation as described above to  $[\widetilde{E}_z]^N$ .

### B. Nonuniform Boundary Problem:

#### Two-Dimensional Process

Notice that if the structure contains metallic strips at the dielectric interface boundary, (5) becomes a set of uncoupled partial differential equations related by the nonuniform boundary conditions (7b) and (7c). In this case, the procedure above is no longer applicable. Instead, a set of fields defined on the lines should be found that satisfies the nonuniform boundary condition. Such a set is actually a mode of the structure. Therefore, the first step of the analysis is to find these modes of the structure. Any given input in the transformed domain can be expanded in terms of these modes. The solution of (5) for the  $i$ th line of the  $n$ th mode which satisfies the transformed boundary condition of (7a) can be written as

$$\widetilde{E}_{zni}(t, y) = \begin{cases} (A_{ni} \cos \omega_{ni}t + B_{ni} \sin \omega_{ni}t) \sin K_{1ni}(b - y) & \text{(in region I)} \\ (A_{ni} \cos \omega_{ni}t + B_{ni} \sin \omega_{ni}t) \cdot (\sin K_{1ni}d / \sin K_{2ni}h) \sin K_{2ni}y & \text{(in region II)} \end{cases} \quad (13)$$

where  $K_{1ni}$ ,  $K_{2ni}$ , and  $\omega_{ni}$  are related by

$$\begin{aligned} K_{1ni}^2 &= \omega_{ni}^2 \mu \epsilon_1 + d_{xxi}^e / (\Delta x)^2 \\ K_{2ni}^2 &= \omega_{ni}^2 \mu \epsilon_2 + d_{xxi}^e / (\Delta x)^2. \end{aligned} \quad (14)$$

Substituting (13) into the transforms of (1a) and (1b), we can find  $\widetilde{H}_{xni}$  and  $\widetilde{H}_{zni}$ . Therefore, the mode current  $[\widetilde{J}_{zni}]$

obtained from the discontinuity of  $[\widetilde{H}_{xni}]$  at  $y = h$  is

$$\begin{aligned} \widetilde{J}_{zni}(t, y = h) &= (-1/\mu) f_{ni}(t) [(\sin K_{1ni}d / \sin K_{2ni}h) \\ &\quad \cdot K_{2ni} \cos K_{2ni} + K_{1ni} \cos K_{2ni}d] \\ &= \widetilde{Y}_{ni}(t, y = h) \widetilde{E}_{zni}(t, y = h) \end{aligned} \quad (15)$$

where

$$\begin{aligned} f_{ni}(t) &= (A_{1ni} \sin \omega_{ni}t / \omega_{ni} - B_{1ni} \cos \omega_{ni}t / \omega_{ni}) \\ \widetilde{Y}_{ni}(t, y = h) &= (-1/\mu) f_{ni}(t) \\ &\quad \cdot (K_{1ni} \cot K_{1ni}d + K_{2ni} \cot K_{2ni}d). \end{aligned}$$

Now, let us apply the final boundary condition (7b) and (7c) on the real field quantity. Because the boundary condition is position dependent, it cannot be directly applied to the transform quantity. Therefore, it is necessary to obtain the inverse transform of  $[\widetilde{J}_{zni}]$ :

$$[J_{zni}(t, y = h)] = [T_x^e] [\widetilde{Y}_{ni}(t, y = h)] \cdot [T_x^e]^t [E_{zni}(t, y = h)] \quad (16)$$

where

$$[\widetilde{Y}_{ni}(t, y = h)] = \text{diag} [\widetilde{Y}_{ni}(t, y = h)].$$

Since  $J_{zni} = 0$  if the  $i$ th line is out of the metallization and  $E_{zni} = 0$  if the  $i$ th line is on the metallization, only the portion of (16) with zero  $[J_{zni}]$  and nonzero  $[E_{zni}]$  provides the characteristic matrix equation:

$$[J_{zni}(t, y = h)]_D = [0] = \left\{ [T_x^e] [\widetilde{Y}_{ni}(t, y = h)] [T_x^e]^t \right\}_{\text{red}} \cdot [E_{zni}(t, y = h)]_D \quad (17)$$

where  $D$  implies that the quantity subscripted by  $D$  is on the nonmetallization portion of the interface and  $\text{red}$  means the reduced portion of (16) obtained by the method described above. In order for the  $n$ th eigenmode,  $[E_{zni}]$ , to satisfy (17) at all times with a nontrivial solution, the time-dependent expression for each line  $i$  should have the same functional form except for a constant factor and the determinant of the reduced matrix should be zero. The final solution of  $[\widetilde{E}_{zni}]$  is

$$\widetilde{E}_{zni}(t, y) = \begin{cases} (A_n \cos \omega_n t + B_n \sin \omega_n t) C_{ni} \sin K_{1ni}(b - y) & \text{(in region I)} \\ (A_n \cos \omega_n t + B_n \sin \omega_n t) \cdot C_{ni} (\sin K_{1ni}d / \sin K_{2ni}h) \sin K_{2ni}y & \text{(in region II)} \end{cases} \quad (18)$$

where  $\omega_n$  is the  $n$ th eigenvalue of the characteristic equation given by

$$\text{Det} \left\{ [T_x^e] [\widetilde{Y}_{ni}(t, y = h)] [T_x^e]^t \right\}_{\text{red}} = 0 \quad (19)$$

and  $C_{ni}$  can be derived from the corresponding eigenvector,  $[E_{zni}]$ , of (17).

The procedure described above is very similar to the frequency-domain method of lines [1], and the  $n$ th eigen-

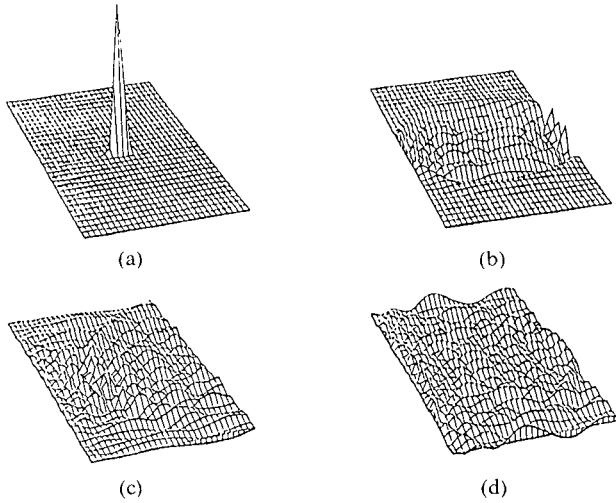


Fig. 3. Distribution of  $E_z$  field at various times obtained by one-dimensional process. (a)  $t = 0$ , (b)  $t = 20$ , (c)  $t = 40$ , and (d)  $t = 60$  [ps].

value,  $\omega_n$ , is actually the  $n$ th cutoff frequency of the given structure. However, the main difference is that we find an eigenvector to obtain a two-dimensional eigenmode of a given structure.

Finally, the transform of any real field can be expanded in terms of the eigenmodes in the transformed domain:

$$\widetilde{E}_{zi}(t, y) = \begin{cases} \sum_n (A_n \cos \omega_n t + B_n \sin \omega_n t) C_{ni} \sin K_{1ni}(b - y) & \text{(in region I)} \\ \sum_n (A_n \cos \omega_n t + B_n \sin \omega_n t) \cdot C_{ni} (\sin K_{1ni} d / \sin K_{2ni} h) \sin K_{2ni} y & \text{(in region II).} \end{cases} \quad (20)$$

The orthogonality property can be used to find  $A_n$  from the initial condition for  $[\widetilde{E}_z(t = 0, y)] = [T_x^e]^t [E_z(t = 0, y)]$ . Also, the causality condition assumed by the time iteration method [3] can be used to find  $B_n$ :

$$B_n = A_n \tan(\omega_n \Delta t / 2)$$

where

$$\Delta t = \Delta x \sqrt{2} \sqrt{\mu \epsilon_{\text{lower}}} \quad (21)$$

The real field at  $y = y_0$  at any time can be obtained by invoking the inverse transformation to the transformed field  $[\widetilde{E}_z(t, y = y_0)]$ . A similar procedure can be used for the TE excitation problem. Even though this two-dimensional process described above is developed for the analysis of the structure with a nonuniform boundary condition, it can also be applied to the problem with a uniform boundary and thus constitutes a generalization of the one-dimensional process described earlier.

### III. RESULTS AND DISCUSSION

The accompanying figures are the result of sample calculations. For comparison, the one-dimensional and two-dimensional processes are used to calculate the  $E_z$  field

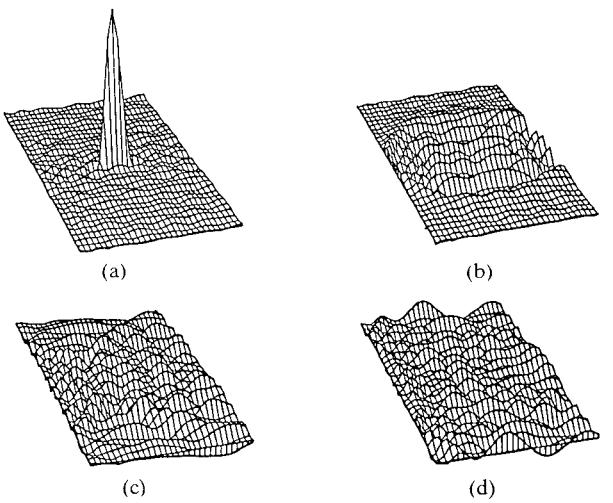


Fig. 4. Distribution of  $E_z$  field at various times obtained by two-dimensional process. (a)  $t = 0$ , (b)  $t = 20$ , (c)  $t = 40$ , and (d)  $t = 60$  [ps].

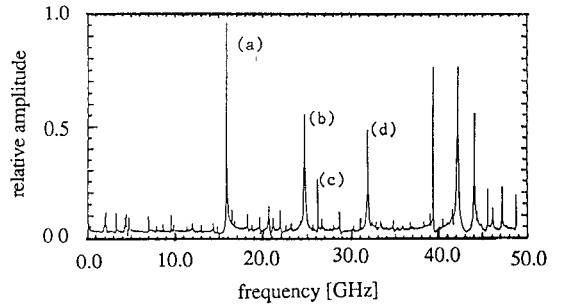


Fig. 5. Cutoff frequency spectrum for the partially filled rectangular waveguide ( $A = 2$ ,  $B = 1$ ,  $h = 0.2$  [cm],  $\epsilon_1 = 1$ ,  $\epsilon_2 = 3$ ). (a)  $\text{TM}_{11}$ , (b)  $\text{TM}_{31}$ , (c)  $\text{TM}_{12}$  and (d)  $\text{TM}_{32}$  etc.

distribution in the partially filled rectangular waveguide after a pulsed  $E_z$  excitation is imposed at  $t = 0$  at the center of the cross section. Figs. 3 and 4 show, respectively, the results obtained by the two different processes. Even though the ripples in the two-dimensional process seem to be slightly higher than those of the one-dimensional process, our results show that both processes can be used to analyze the wave propagation characteristics in the time domain. One thing to be noticed here is that although the one-dimensional process is simple and efficient, it cannot be applied to problems with nonuniform boundary conditions. Fig. 5 shows the spectrum of the time signal for  $E_z$  obtained by the one-dimensional process, where the waveguide cutoff frequencies correspond to the peaks in the spectrum. The results differ by less than 1 percent from the analytical values. For confirmation of the two-dimensional process, the eigenfrequency of the finned rectangular waveguide for the dominant TE mode is calculated by the characteristic equation (19) and compared with Hoefer's result [4] in Fig. 6. Good agreement is obtained. The result for pulse propagation and scattering in the finned rectangular waveguide obtained by the two-dimensional process is shown in Fig. 7.

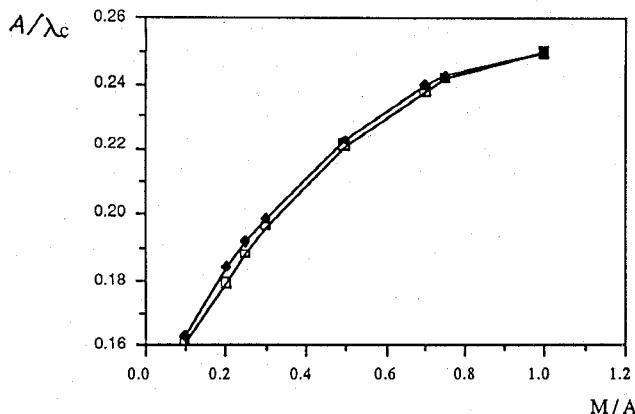


Fig. 6. Cutoff frequency of the finned waveguide shown in Fig. 1 with  $B/A = 2$ ,  $h = 1$ . (Light squares: present method. Dark squares: Hoefer [4].)

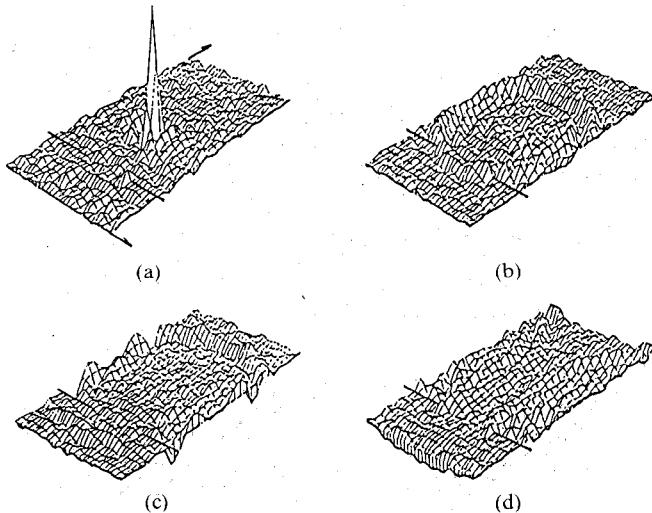


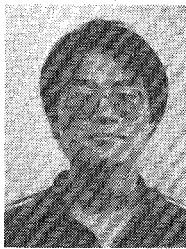
Fig. 7. The picture of a pulse propagation in a finned rectangular waveguide ( $A = 1$ ,  $B = 2$ ,  $h = 0.5$  [cm], and  $\epsilon_r = 3$ ) at time (a)  $t = 0$ , (b)  $t = 30$ , (c)  $t = 40$ , and (d)  $t = 60$  [ps].

#### IV. CONCLUSIONS

In this paper, we showed that the time-domain method of lines can be used to analyze planar transmission structures. It is accomplished by the one-dimensional or the two-dimensional eigenmode expansion concept depending on the uniformity of the interface boundary condition along the transformed direction. The proposed time-domain method can be applied to analyze three-dimensional wave propagation problems in the time domain.

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